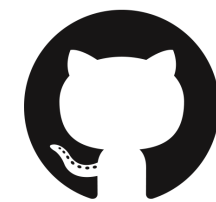


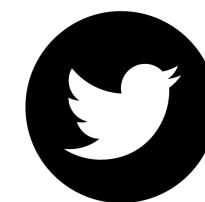
# Evolutionary Reinforcement Learning

Jean-Baptiste Mouret

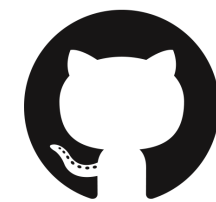
Dennis G. Wilson



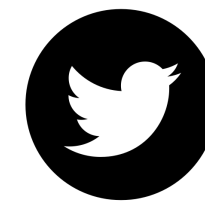
@jbmouret



@jb\_mouret

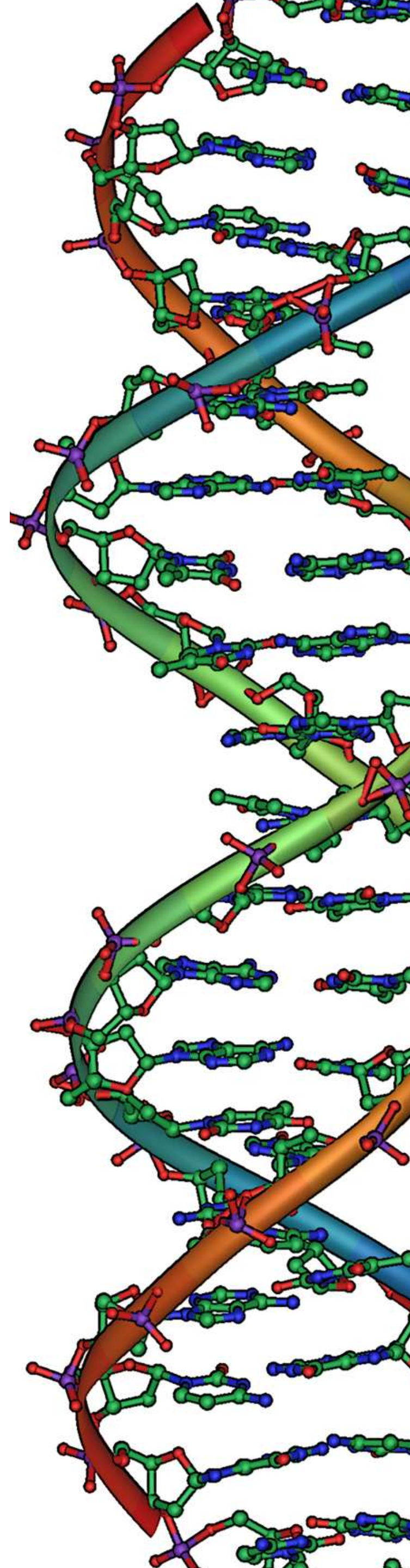


@d9w



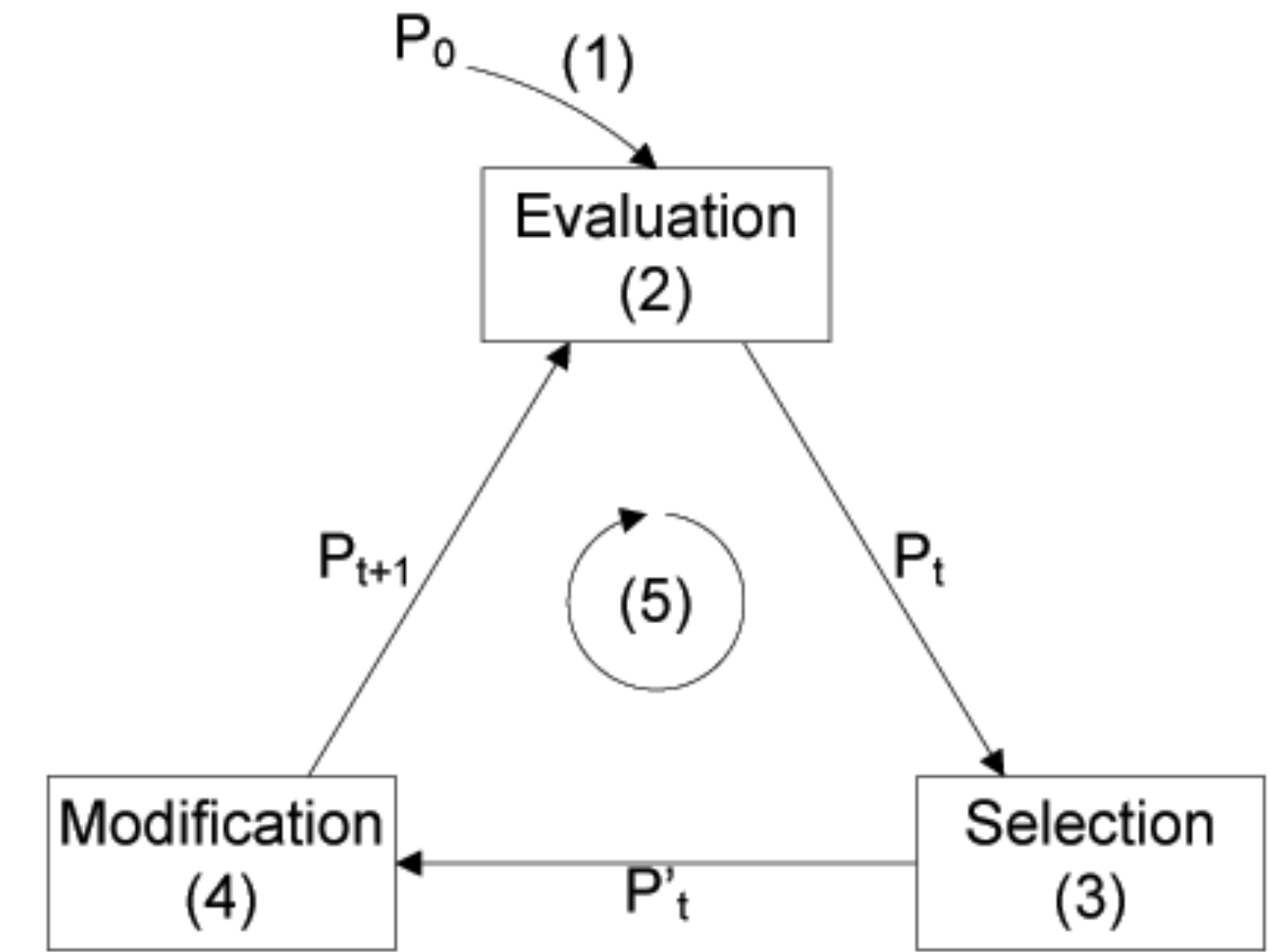
@digiwilson

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# Evolution on computers

- Evolution is one of the most fundamental “algorithms” of life
- It is **iterative** (generation by generation)
- It works by **trial-and-error**
  - random mutation = exploration
  - fitness = reward
- Evolution solves a trial-and-error learning problem! like reinforcement learning
  - another metaphor (give other ideas / challenges)
  - a long history in computing (at least as long as learning)



# Evolution can optimize policies

like PPO/TRPO/etc.

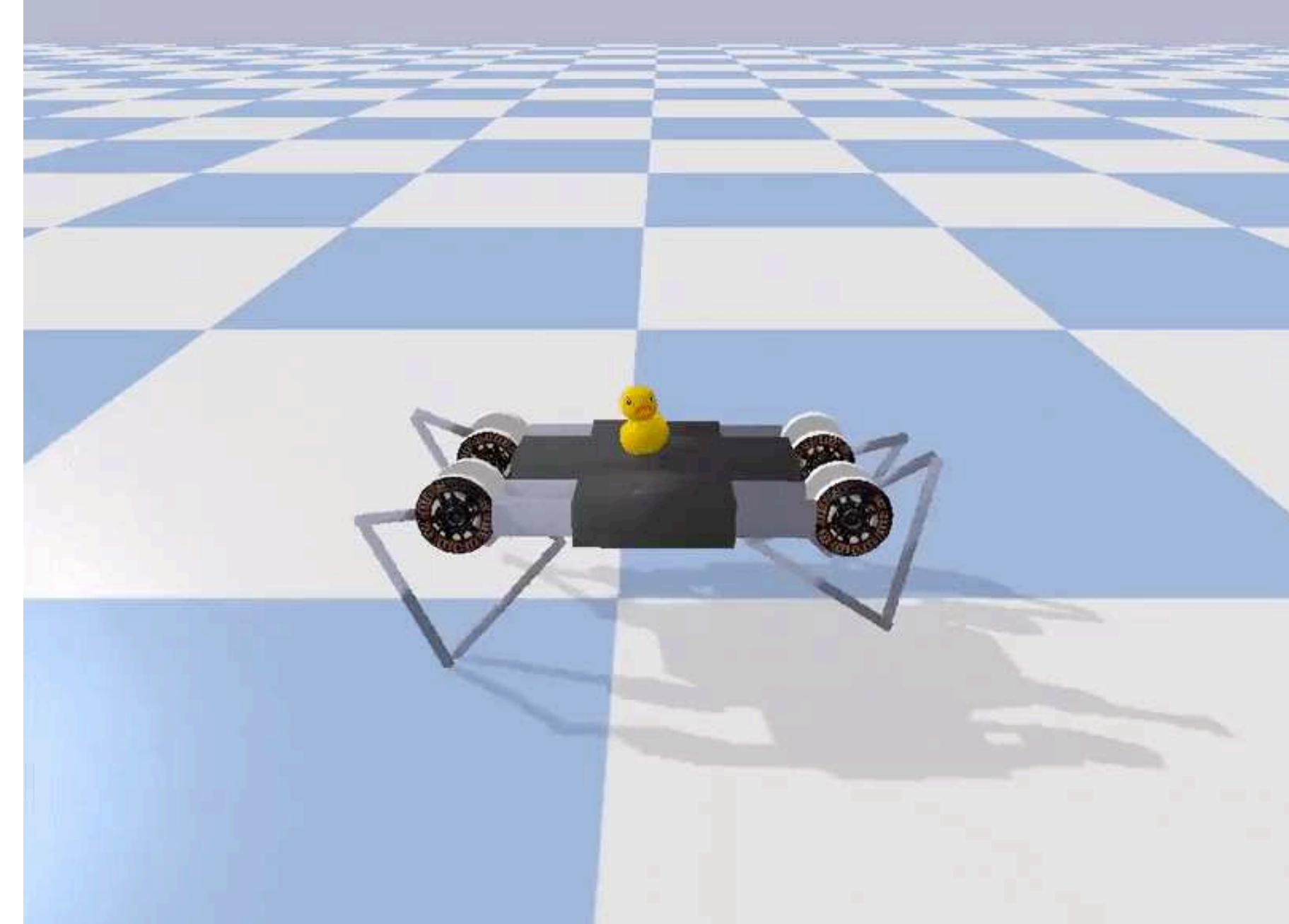
Optimize:  $J(\theta) = \mathbb{E} \left[ \sum_{t=1}^T r(\mathbf{x}_t) \mid \theta \right]$

Parameters of the policy  $\theta$  (indicated by a cyan arrow pointing up to  $\theta$ )

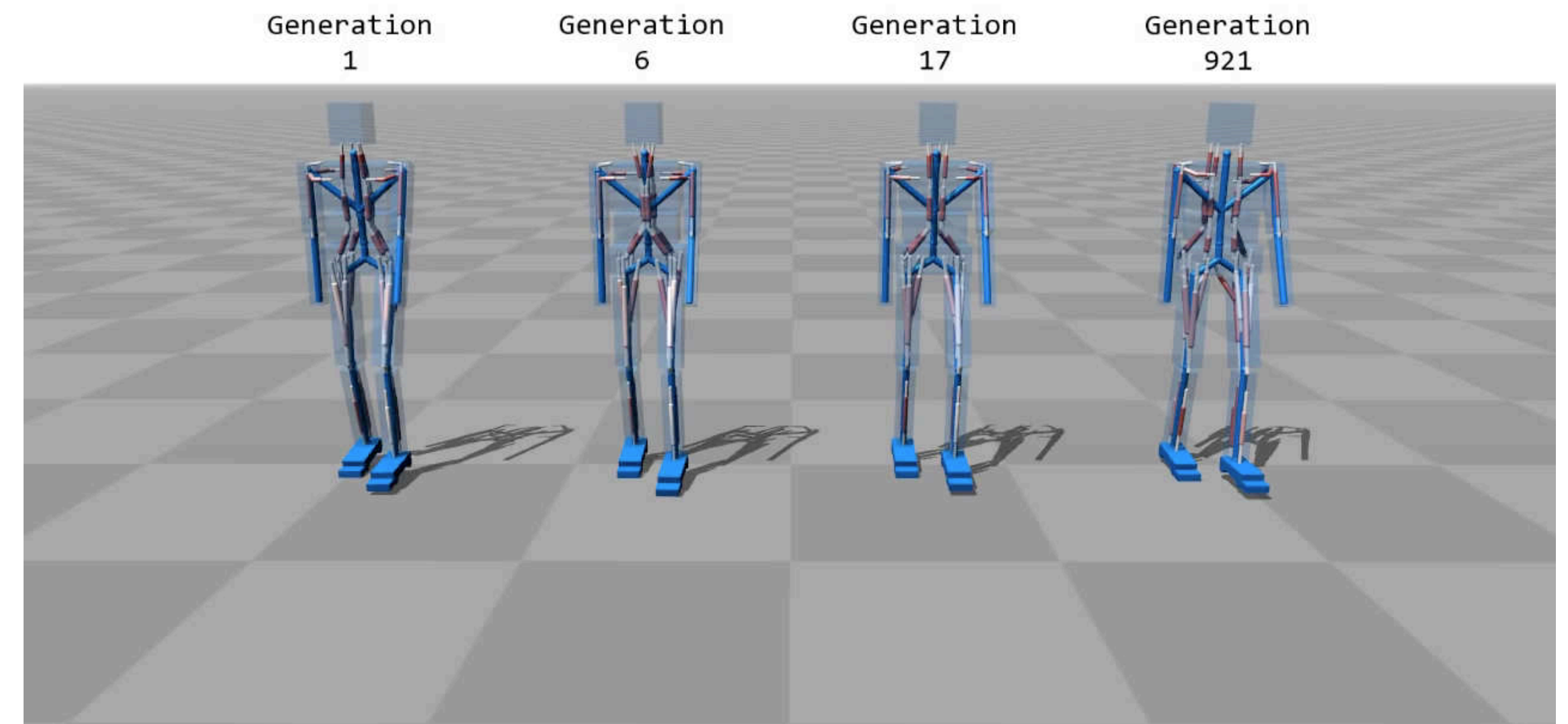
Reward for state  $\mathbf{x}_t$  (indicated by a red arrow pointing down to  $r(\mathbf{x}_t)$ )

$J(\theta)$  (indicated by a yellow arrow pointing down)

- Black-box optimizer (no gradient)
- Multi-objective (Pareto-based) optimization
- Scale to parallel computers easily
- Holistic view (discard intermediate steps)
  - no credit assignment problem
  - no problem with large (continuous) states
- ... but discard a lot of useful data



<https://blog.otoro.net/2017/11/12/evolving-stable-strategies/>



Geijtenbeek, T., van de Panne, M., & van der Stappen, A. F. (2013). "Flexible muscle-based locomotion for bipedal creatures". *ACM Transactions on Graphics (TOG)*, 32(6), 206.

# Evolution can optimize structures

neural architecture search, morphology

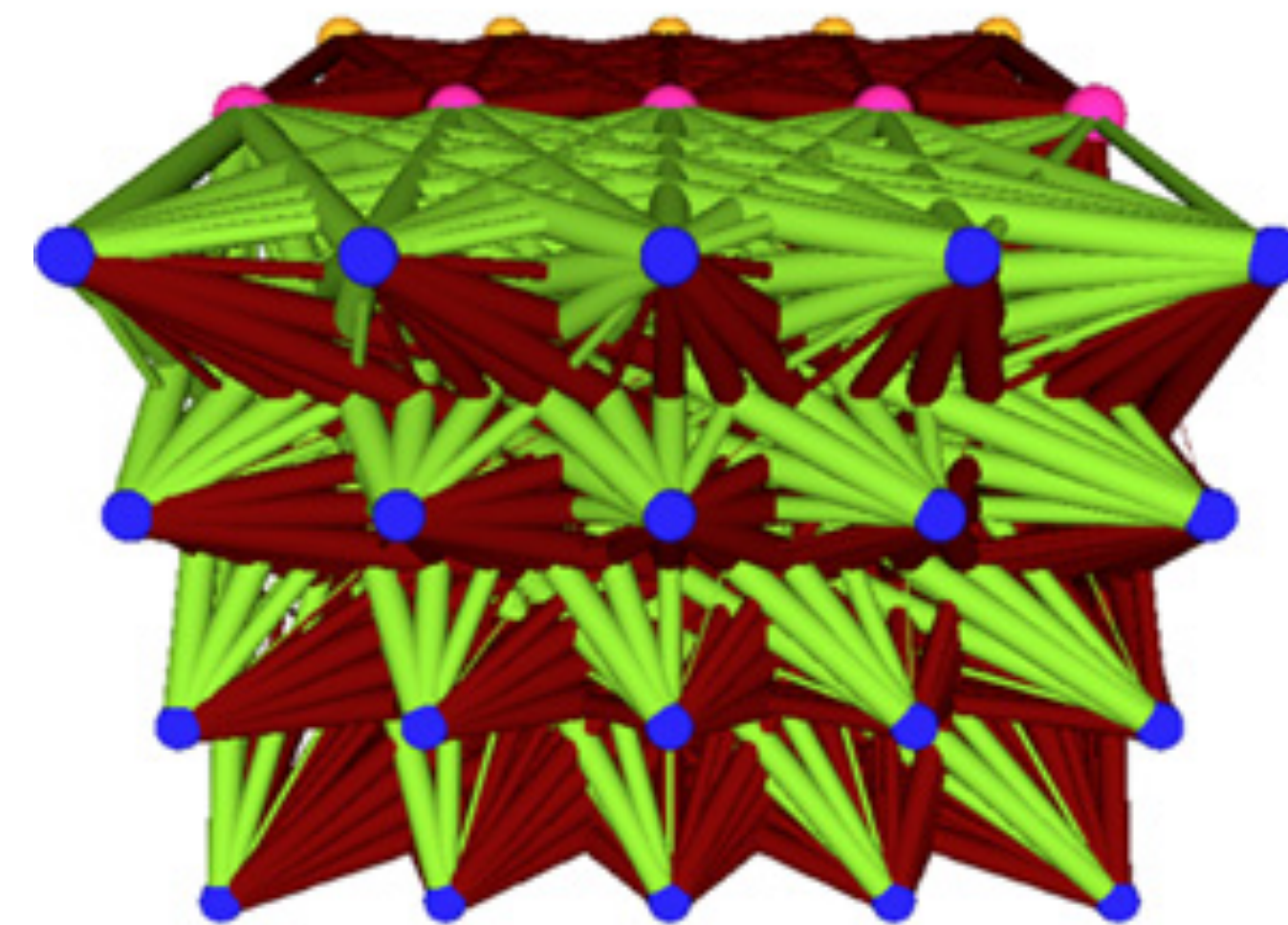
A question that was studied for a very long time in evolution!



**Sims, Karl. (1994)** "Evolving 3D morphology and behavior by competition."

*Artificial life* 1.4 (1994): 353-372.

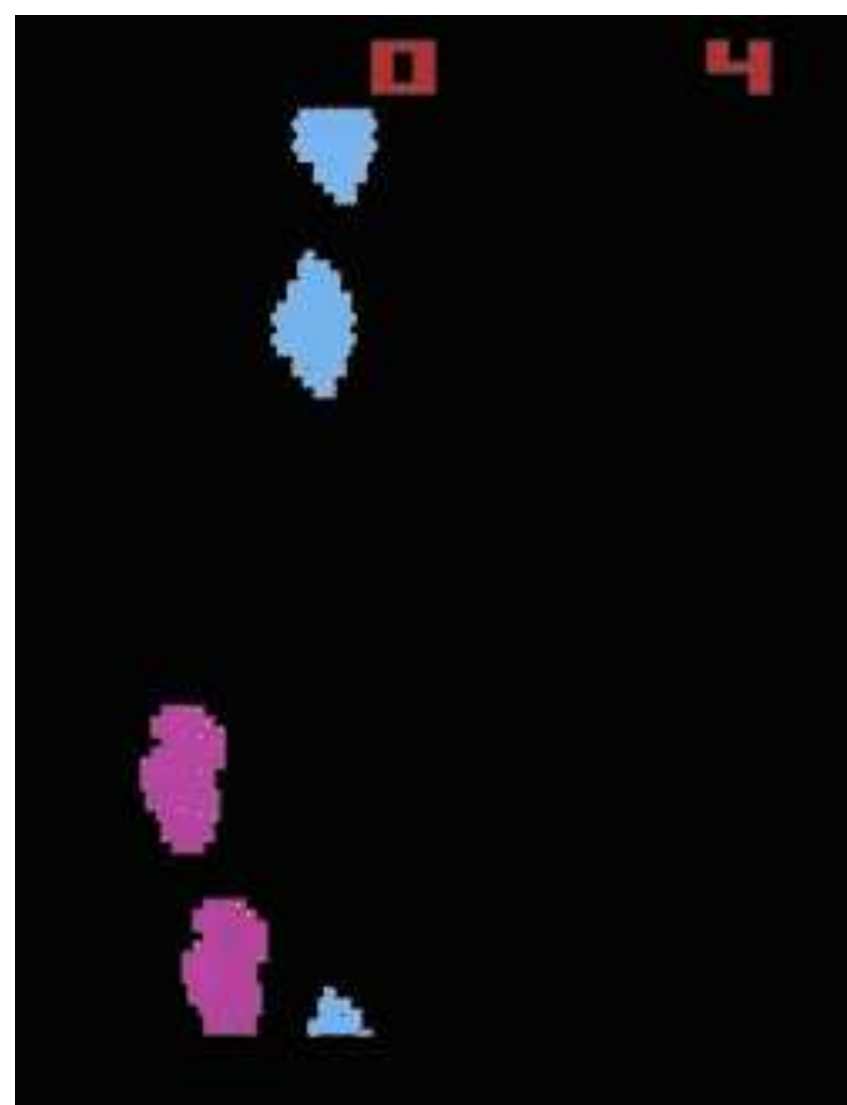
repeat for each node



**Clune J, Stanley KO, Pennock RT, Ofria**

**C. (2011)** On the performance of indirect encoding across the continuum of regularity. *IEEE Transactions on Evolutionary Computation*. 2011 Jun;15(3):346-67.

# Evolution can be competitive for deep RL tasks



	DQN	ES	A3C	RS	GA	GA
Frames	200M	1B	1B	1B	1B	6B
Time	~7-10d	~ 1h	~ 4d	~ 1h or 4h	~ 1h or 4h	~ 6h or 24h
Forward Passes	450M	250M	250M	250M	250M	1.5B
Backward Passes	400M	0	250M	0	0	0
Operations	1.25B U	250M U	1B U	250M U	250M U	1.5B U
amidar	<b>978</b>	112	264	143	263	377
assault	4,280	1,674	<b>5,475</b>	649	714	814
asterix	4,359	1,440	<b>22,140</b>	1,197	1,850	2,255
asteroids	1,365	1,562	<b>4,475</b>	1,307	1,661	2,700
atlantis	279,987	<b>1,267,410</b>	911,091	26,371	76,273	129,167
enduro	<b>729</b>	95	-82	36	60	80
frostbite	797	370	191	1,164	<b>4,536</b>	<b>6,220</b>
gravitar	473	<b>805</b>	304	431	476	764
kangaroo	7,259	<b>11,200</b>	94	1,099	3,790	<b>11,254</b>
seaquest	<b>5,861</b>	1,390	2,355	503	798	850
skiing	-13,062	-15,443	-10,911	-7,679	† <b>-6,502</b>	† <b>-5,541</b>
venture	163	760	23	488	<b>969</b>	† <b>1,422</b>
zaxxon	5,363	6,380	<b>24,622</b>	2,538	6,180	7,864

Such FP, Madhavan V, Conti E, Lehman J, Stanley KO, Clune J. Deep neuroevolution: Genetic algorithms are a competitive alternative for training deep neural networks for reinforcement learning. arXiv preprint arXiv:1712.06567. 2017.

# Outline

## 1. Evolutionary Strategies

*from  $(\mu, \lambda)$ -ES to CMA-ES*

## 2. Pareto-based Multi-objective evolutionary algorithms

*NSGA-II*

## 3. Neuroevolution

*from NEAT to HyperNEAT*

## 4. Beyond the fitness function

*from novelty search to quality diversity*

## **Keynote: Sebastian Risi (IT University of Copenhagen)**

*Evolving Agents that Learn More Like Animals*

## **Choices:**

- ➔ *introduce the “classic algorithms” of the field (not always the most competitive)*
- ➔ *present a few algorithms “in depth” (we will not be exhaustive at all)*
- ➔ *In many cases, a notebook makes it possible to reproduce the examples*